

Natural Language Processing

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Part 1: Linear models for Tagging

Tagging tasks in NLP

Log-linear models for Tagging

Tagging Tasks

Tagged Sequences a b e e a f h j \Rightarrow a/Y b/Z e/Y e/Y a/Z f/X h/Z j/Y

Example 1: Part-of-speech tagging

Profits/N soared/V at/P Boeing/N Co./N ,/, easily/ADV topping/V forecasts/N on/P Wall/N Street/N ,/, as/P their/POSS CEO/N Alan/N Mulally/N announced/V first/ADJ quarter/N results/N ./.

Example 2: Named Entity Recognition

Profits/O soared/O at/O Boeing/B-CO Co./I-CO ,/O easily/O topping/O forecasts/O on/O Wall/B-LOC Street/I-LOC ,/O as/O their/O CEO/O Alan/B-PER Mulally/I-PER announced/O first/O quarter/O results/O ./O

Notation for Tagging Tasks

- Set of possible input words: V
- Set of possible tags: T
- Word sequence: $x_{[1:n]} = [x_1, \ldots, x_n]$
- Tag sequence: $t_{[1:n]} = [t_1, \ldots, t_n]$
- Training data is N tagged sentences, the *ith* sentence has length n_i:

$$(x_{[1:n]}^{(i)}, t_{[1:n]}^{(i)})$$
 for $i = 1, ..., n$

Independence Assumptions for Tagging Chain Rule

$$P(t_{[1:n]} \mid x_{[1:n]}) = \prod_{j=1}^{n} P(t_j \mid t_{j-1}, \dots, t_1, x_{[1:n]}, j)$$

Make independence assumptions

$$P(t_{[1:n]} | x_{[1:n]}) \approx \prod_{j=1}^{n} P(t_j | t_{j-1}, x_{[1:n]}, j)$$

j is the word being tagged.

We model the conditional probability directly: no Bayes Rule here.

Questions

• How to find $\arg \max_{t_{[1:n]}} P(t_{[1:n]} | x_{[1:n]})?$

Tagging tasks in NLP

Log-linear models for Tagging

Representation: finding the right parameters

Problem: Predict ?? using context, P(?? | context)

 $\mathsf{Profits}/\mathsf{N}\xspace$ soared/V at/P $\mathsf{Boeing}/\ref{eq:soared}$ Co. , easily topping forecasts on Wall Street , as their CEO Alan Mulally announced first quarter results .

Representation: history

- A history is a 3-tuple: $(t_{-1}, x_{[1:n]}, i)$
- t_{-1} is the previous tag (we are assuming a bigram model)

- *i* is the index of the word being tagged
- For example, for x_4 = Boeing:

•
$$t_{-1} = P$$

• $x_{[1:n]} = (Profits, soared, ..., results, .)$
• $i = 4$

Feature-vectors over history-tag pairs

Take a history, tag pair (h, t)

 $f_k(h, t)$ for k = 1, ..., m are **feature functions** representing the tagging decision.

Example: Part-of-speech tagging [Ratnaparkhi 1996]

$$f_{100}(h,t) = \begin{cases} 1 & \text{if current word } x_i \text{ is Boeing and } t = \mathbb{N} \\ 0 & \text{otherwise} \end{cases}$$

$$f_{101}(h,t) = \begin{cases} 1 & \text{if } t_{-1} \text{ is } P \text{ and } t = N \\ 0 & \text{otherwise} \end{cases}$$

Log linear model for Tagging

• Let there be *m* features, $f_k(\mathbf{x}, \mathbf{y})$ for k = 1, ..., m

•
$$\mathbf{x} = x_{[1:n]}$$
 and $\mathbf{y} = t_{[1:n]}$

- Define a parameter vector $\mathbf{w} \in \mathbb{R}^m$
- Each (x, y) pair is mapped to score:

$$s(\mathbf{x},\mathbf{y}) = \sum_{k} w_k \cdot f_k(\mathbf{x},\mathbf{y})$$

Using inner product notation:

$$\mathbf{w} \cdot \mathbf{f}(\mathbf{x}, \mathbf{y}) = \sum_{k} w_{k} \cdot f_{k}(\mathbf{x}, \mathbf{y})$$

 $\mathbf{s}(\mathbf{x}, \mathbf{y}) = \mathbf{w} \cdot \mathbf{f}(\mathbf{x}, \mathbf{y})$

To get a probability from the score: Renormalize!

$$\mathsf{Pr}(\mathbf{y} \mid \mathbf{x}, \mathbf{w}) = \frac{exp(s(\mathbf{x}, \mathbf{y}))}{\sum_{\mathbf{y}'} exp(s(\mathbf{x}, \mathbf{y'}))}$$

Feature functions for Tagging

Problem

- We have defined a log-linear model using feature functions: f(x,y)
- We have defined parameters using a history h so feature functions are: f(h, t)

Locally normalized log-linear taggers

Conditional Distribution over history, tag pair (h, t)

$$\log \Pr(t \mid h) = \mathbf{w} \cdot \mathbf{f}(h, t) - \log \sum_{t'} \exp \left(\mathbf{w} \cdot \mathbf{f}(h, t') \right)$$

w is the weight vector

Local normalization for tagging

Word sequence: x_[1:n] and tag sequence: t_[1:n]

• Histories
$$h_i = (t_{i-1}, x_{[1:n]}, i)$$

$$\log \Pr(t_{[1:n]} \mid x_{[1:n]}) = \sum_{i=1}^{n} \log \Pr(t_i \mid h_i)$$

Globally normalized log-linear taggers

Global feature function $\Phi(x, y)$

- Word sequence: $\mathbf{x} = x_{[1:n]}$ and tag sequence: $\mathbf{y} = t_{[1:n]}$
- From *local* histories $h_i = (t_{i-1}, x_{[1:n]}, i)$ to global Φ values:

$$\Phi_k(x_{[1:n]}, t_{[1:n]}) = \sum_{i=1}^n f_k(h_i, t_i)$$

Φ(x, y) = (Φ₁, Φ₂, ..., Φ_m) is a *global* feature vector
w is the weight vector for Φ

Global normalization for tagging

$$\log \mathsf{Pr}(\mathbf{y} \mid \mathbf{x}, \mathbf{w}) = \mathbf{w} \cdot \mathbf{\Phi}(\mathbf{x}, \mathbf{y}) - \log \sum_{\mathbf{y}'} exp\left(\mathbf{w} \cdot \mathbf{\Phi}(\mathbf{x}, \mathbf{y'})\right)$$

Conditional Random Field

Global normalization for tagging

$$\log \mathsf{Pr}(\mathbf{y} \mid \mathbf{x}, \mathbf{w}) = \mathbf{w} \cdot \mathbf{\Phi}(\mathbf{x}, \mathbf{y}) - \log \sum_{\mathbf{y}'} exp\left(\mathbf{w} \cdot \mathbf{\Phi}(\mathbf{x}, \mathbf{y}')\right)$$

This model is also called a conditional random field (CRF)

Algorithms for training and decoding

- Global normalization could be expensive: requires sum over exponentially many terms y'
- Finding arg maxy log Pr(y | x) can be accomplished using the Viterbi algorithm.
- Training: finding the weight vector w can be done using a variant of the Forward algorithm.

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