

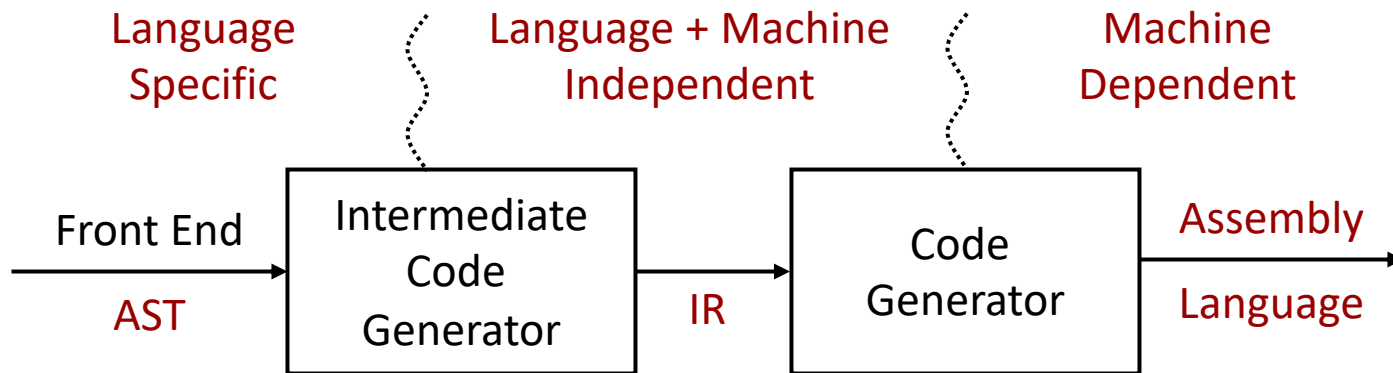
Intermediate Representation

CMPT 379: Compilers

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Intermediate Representation



Provides an intermediate level of abstraction

- More details than source (programming language)
- Fewer details than target (assembly language)

IR: 3-Address Code

- High level assembly
- Instructions that operate on named locations and labels
- Locations
 - Each location is some place to store 4 bytes
 - Pretend we can make infinitely many of them
 - Or global variable
 - Referred to by global name
- Labels (you generate as needed)
- 3-address code = **at most** three addresses/locations in each instructions

IR: 3-Address Code

- Address or locations:
 - Names/Labels
 - Constants
 - Temporaries

IR: 3-Address Code

For simplicity, in these slides we will omit the type of each address/location. In real IR (like LLVM) the type and alignment for each location has to be defined.

- Instructions:

- assignments:

- $x = y \text{ op } z$ (op: binary arithmetic or logical operation)
 - $x = \text{op } y$ (op: unary operation)

- copy: $x = y$

- unconditional jump:

- `goto L` (*L is a symbolic label of a statement*)

- conditional jumps:

- `if x goto L`
 - `IfFalse x goto L`
 - `if x relop y goto L` (*relop: relation operator: <,==,<=*)

IR: 3-Address Code

Instructions:

- Function/procedure calls: $p(x_1, x_2, \dots, x_n)$

- param x_1

- param x_2

- ...

- param x_n

- $y = \text{call } p, n$

In LLVM:

$r = \text{call } \langle \text{return-type} \rangle p(\langle \text{type} \rangle x_1, \langle \text{type} \rangle x_2, \dots, \langle \text{type} \rangle x_n)$

- Return statement:

- return y

- You can save the return: $y = \text{call } p()$ or if it is a void return: $\text{call } p()$

IR: 3-Address Code

Instructions:

- Indexed assignments (Arrays):
 - $x = y[i]$
 - $x[i] = y$
- Address assignments:
 - $x = \&y$ (which sets x to the location of y)
- Pointer assignments:
 - $x = *y$ (*y is a pointer, sets x to the value pointed by y*)
 - $*x = y$

Basic Blocks and Control Flow

Basic Blocks

- A *basic block* is a sequence of statements that enters at the start and ends with a branch at the end
- Functions transfer control from one place (the caller) to another (the called function)
- Other examples include any place where there are branch instructions
- Code generation should create code for basic blocks and branch them together

Control Flow

Consider the statement:

```
while (a[i] < v) { i = i+1; }
```

```
L1:
  t1 = i
  t2 = t1 * 8
  t3 = a[ t2 ]
  t4 = t3 < v
  ifFalse t4 goto L2
  t5 = i
  t5 = t5 + 1
  i = t4
  goto L1
L2: ...
```

Labels can be
implemented using
position numbers

```
100: t1 = i
101: t2 = t1 * 8
102: t3 = a[ t2 ]
103: t4 = t3 < v
104: ifFalse t4 goto 109
105: t5 = i
106: t5 = t5 + 1
107: i = t5
108: goto 100
109:
```

Basic Blocks

Consider the statement:

```
while (a[i] < v) { i = i+1; }
```

Basic Block

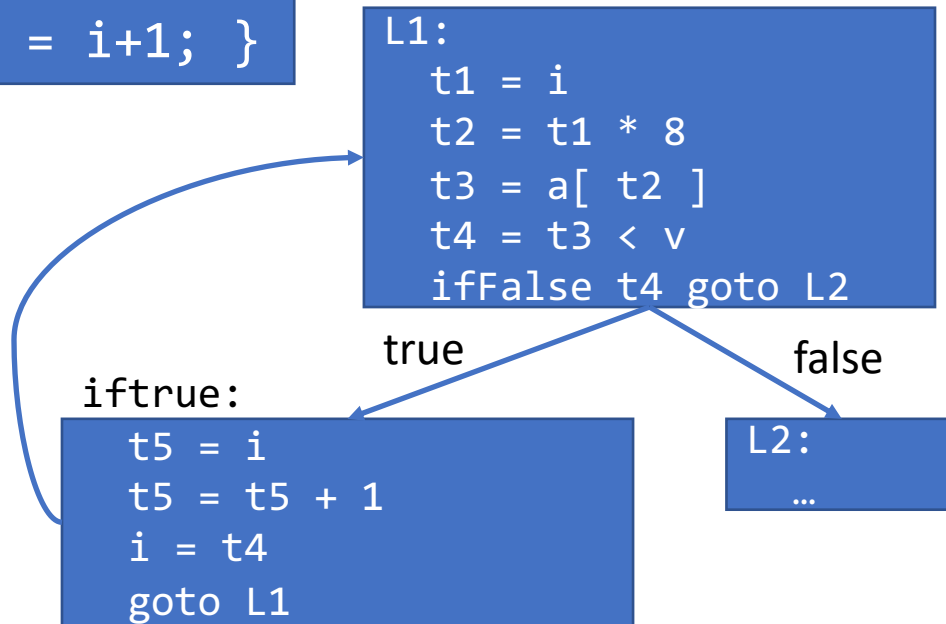
```
L1:  
t1 = i  
t2 = t1 * 8  
t3 = a[ t2 ]  
t4 = t3 < v  
ifFalse t4 goto L2
```

BB

```
t5 = i  
t5 = t5 + 1  
i = t4  
goto L1
```

BB

```
L2: ...
```



```
int gcd(int x, int y)
{
    int d;
    d = x - y;
    if (d > 0)
        return gcd(d, y);
    else if (d < 0)
        return gcd(x, -d);
    else
        return x;
}
```

```
gcd:
    t0 = x - y
    d = t0
    t1 = d
    t2 = t1 > 0
    ifFalse t2 goto L0
    t3 = call gcd(d,y)
    return t3

L0:
    t4 = d
    t5 = t4 < 0
    ...
```

Avoiding redundant gotos:
if t2 goto L1
goto L0
L1: ...

Short-circuiting Booleans

- More complex if statements:

- if (a or b and not c) { ... }

- Typical sequence:

- t1 = not c

- t2 = b and t1

- t3 = a or t2

- Short-circuit is possible in this case:

- if (a and b and c) { ... }

- Short-circuit sequence:

- t1 = a

- if t1 goto L0 /* sckt */

- goto L4

- L0:

- t2 = b

- if t2 goto L1

- goto L4

- L1:

- t3 = c

- ...

```
void main() {  
    int i;  
    for (i = 0; i < 10; i = i + 1)  
        print(i);  
}
```

More Control Flow:
for loops

```
main:  
    t0 = 0  
    i = t0  
L0:  
    t1 = 10  
    t2 = i < t1  
    ifFalse t2 goto L1  
    call print(i)  
    t3 = 1  
    t4 = i + t3  
    i = t4  
    goto L0  
L1:  
    return
```

Translation of Expressions

symbol table

$S \rightarrow id = E$ `{ $$$$.code=concat($\$3$.code, $\$1$.lexeme= $\$3$.addr);}`

$E \rightarrow E + E$ `{ $$$$.addr=new Temp(); $$$$.code=concat($\$1$.code,
 $\$3$.code, $$$$.addr = $\$1$.addr + $\$3$.addr);}`

$E \rightarrow - E$ `{ $$$$.addr = new Temp(); $$$$.code = concat($\$2$.code,
 $$$$.addr = - $\$2$.addr);}`

$E \rightarrow (E)$ `{ $$$$.addr = $\$2$.addr; $$$$.code = $\$2$.code;}`

$E \rightarrow id$ `{ $$$$.addr = symtbl($\$1$.lexeme); $$$$.code = new Code();}`

Backpatching in Control-Flow

- Implementing the translations can be done in one or two passes
- The difficulty with code generation in one pass is that we may not know the target label for jump statements
- *Backpatching* allows one pass code generation
 - Generate jump statements with the empty targets (temporarily unspecified)
 - Put each of these statements into a list
 - When the target is known, fill the proper labels in the jump statements (backpatching)
 - In some IR libraries (like LLVM) we can create multiple locations and set them as insert points

Control Flow using an IR that supports multiple insertion points

Control flow: if statements

if (a < b) then i = i+1; else j = i+1;

```
func = Builder.GetInsertBlock()->getParent();  
BasicBlock::Create(C, "if", func);  
CreateBr(IfBB);
```

```
if:  
  t0 = a < b  
  if t0 goto ???
```

true

```
IfTrueBB = BasicBlock::Create(C, "true", func);  
syms.enter_symtbl("true", IfTrueBB);  
Builder.SetInsertPoint(IfTrueBB);
```

```
true:  
  t1 = 1  
  t2 = i + t1  
  i = t2  
  goto ???
```

goto end

false

```
IfFalseBB = BasicBlock::Create(C, "else", func);  
syms.enter_symtbl("else", IfFalseBB);  
Builder.SetInsertPoint(IfFalseBB);
```

```
else:  
  t1 = 1  
  t2 = i+t1  
  j = t2  
  goto ???
```

```
EndBB = BasicBlock::Create(C, "end", func);  
syms.enter_symtbl("end", EndBB);  
Builder.SetInsertPoint(EndBB);
```

```
end:
```

Q: What would be the goto target for a continue statement in the body: basic block?

Control flow: while statements

```
while (i < n) { break; i = i+1; }
```

```
func = Builder.GetInsertBlock()->getParent();
LoopBB = BasicBlock::Create(C, "loop", func);
CreateBr(LoopBB);
```

```
loop:
  t0 = i < n
  if t0 goto ???
```

i2 = phi(i1,i3)
t0 = i2 < n

true

goto body

false

```
EndBB = BasicBlock::Create(C, "end", func);
syms.enter_symtbl("end", EndBB);
Builder.SetInsertPoint(EndBB);
```

end:

```
BodyBB = BasicBlock::Create(C, "body", func);
syms.enter_symtbl("body", BodyBB);
Builder.SetInsertPoint(BodyBB);
```

```
body:
  t1 = 1
  t2 = i + t1
  i = t2
  goto ???
```

goto end

t2 = i2 + t1

i3 = t2

Control flow: for statements

Q: What would be the goto target for a break/continue statement(s) in the body: basic block?

```
for (i=0; i<n; i=i+1) { c=i; }  
      continue;
```

```
init:  
  i = 0  
  goto ???
```

```
func = Builder.GetInsertBlock()->getParent();  
LoopBB = BasicBlock::Create(C, "loop", func);  
CreateBr(LoopBB);
```

```
loop:  
  t0 = i < n  
  if t0 goto ???
```

true

false

```
EndBB = BasicBlock::Create(C, "end", func);  
syms.enter_symtbl("end", EndBB);  
Builder.SetInsertPoint(EndBB);
```

```
end:
```

```
BodyBB = BasicBlock::Create(C, "body", func);  
syms.enter_symtbl("body", BodyBB);  
Builder.SetInsertPoint(BodyBB);
```

```
body:  
  c = i  
  goto ???
```

goto next

```
NextBB = BasicBlock::Create(C, "next", func);  
syms.enter_symtbl("next", NextBB);  
Builder.SetInsertPoint(NextBB);
```

```
next:  
  t1 = 1  
  t2 = i + t1  
  i = t2  
  goto ???
```

Backpatching for an IR that only supports line numbers

Backpatching

If (a < b) then i = i+1; else j = i+1;

99: t0 = a < b

100: if t0 goto ???

101: goto ???

102: t1 = 1

103: t2 = i + t1

104: i = t2

105: goto ???

106: t1 = 1

107: t2 = i+t1

108: j = t2

109:

truelist

falselist

nextlist

backpatch({100}, 102)

backpatch({101}, 106)

backpatch({105}, 109)

Backpatching

- We maintain a list of statements that need patching by future statements
- Three lists are maintained:
 - truelist: for targets when evaluation is true
 - falselist: for targets when evaluation is false
 - nextlist: the statement that ends the block (also used for loops)
- These lists can be implemented as a synthesized attribute
 - Using marker non-terminals

- $S \rightarrow \text{if "(" B "}") M block}$
 { backpatch(\$3.truelist, \$5.instr);
 \$\$nextlist = merge(\$3.falselist, \$6.nextlist); }
- $B \rightarrow E \text{ rel } E$ next instruction number
 { \$\$truelist = makelist(nextinstr+1);
 \$\$falselist = makelist(nextinstr+2);
 Code+="c = \$1.addr \$2.op \$3.addr";
 Code+="if c goto -";
 Code+="goto -"; }
- $B \rightarrow \text{true}$
 { \$\$truelist=makelist(nextinstr); Code+="goto -"; }
- $B \rightarrow \text{false}$
 { \$\$falselist=makelist(nextinstr); Code+="goto -"; }
- $M \rightarrow \varepsilon$ { \$\$instr = nextinstr; }

If (a < b) {i = i+1;}

- 101: c = a < b
- 102: if c goto - 104
- 103: goto - 107
- 104: t1 = 1
- 105: t2 = i+t1
- 106: i = t2
- 107:

B.truelist={102},

B.falselist={103}

M.instr = 104

backpatch({102}, 104)

S.nextlist={103}

backpatch({103}, 107)

- $S \rightarrow \text{while } M \text{ "(" } B \text{ ")" } M \text{ block}$

```
{ backpatch($7.nextlist, $2.instr);
  backpatch($4.truelist, $6.instr);
  backpatch($4.falselist, $7.nextlist);
  $$nextlist = merge($4.falselist, $7.breaklist);
  Code+="goto $2.instr";}
```
- $S \rightarrow \text{"break"};$

```
{ $$breaklist=makelist(nextinstr); Code+="goto -";}
```
- $S \rightarrow \text{"continue"};$

```
{ $$nextlist=makelist(nextinstr); Code+="goto -"; }
```
- $B \rightarrow E \text{ rel } E \text{ } \{ /* \text{ same as previous slide } /* \}$
- $\text{block} \rightarrow \text{"{" } S \text{ "}"}$

```
{ $$breaklist=$2.breaklist;
  $$nextlist=$2.nextlist; }
```
- $M \rightarrow \epsilon \text{ } \{ \$$.instr = nextinstr; \}$

```
while (i < n) {continue;}
```

- 101: $c = i < n$
- 102: if c goto – 104
- 103: goto – 105
- 104: goto – 101
- 105:

$M(\$4).instr = 101$

$B.truelist=\{102\}, B.falselist=\{103\}$

$M(\$6).instr = 104$

$S(\$3).nextlist=block(\$7).nextlist=\{105\}$

$backpatch(\{102\}, 104)$

$backpatch(\{103\}, 105)$

$S.nextlist=\{105\}$

- $S \rightarrow \text{while } M "(" B ")" M \text{ block}$
 $\{\text{backpatch}(\$7.\text{nextlist}, \$2.\text{instr});$
 $\text{backpatch}(\$4.\text{truelist}, \$6.\text{instr});$
 $\$$.nextlist = \text{merge}(\$4.\text{falselist}; \$7.\text{breaklist}); \}$
 $\text{Code} += \text{"goto } \$2.\text{instr"}; \}$
- $S \rightarrow \text{break ;}$
 $\{\$$.breaklist = \text{makelist}(\text{nextinstr}); \text{Code} += \text{"goto -"}; \}$
- $S \rightarrow \text{continue ;}$
 $\{\$$.nextlist = \text{makelist}(\text{nextinstr}); \text{Code} += \text{"goto -"}; \}$
- $B \rightarrow E \text{ rel } E \text{ } \{ /* \text{ same previous slide } */ \}$
- $\text{block} \rightarrow "{" S "}"$
 $\{\$$.breaklist = \$2.breaklist;$
 $\$$.nextlist = \$2.nextlist; \}$
- $M \rightarrow \varepsilon \text{ } \{\$$.instr = \text{nextinstr}; \}$

$\text{while } (i < n) \{ \text{break}; \}$

- 101: $c = i < n$
- 102: $\text{if } i < n \text{ goto - } 104$
- 103: $\text{goto - } 105$
- 104: $\text{goto - } 105$
- 105: $\text{goto } 101$

$M(\$2).\text{instr} = 101$

$B.\text{truelist} = \{102\}, B.\text{falselist} = \{103\}$

$M(\$6).\text{instr} = 104$

$S(\$3).\text{breaklist} = \text{block}.\text{breaklist} = \{104\}$

$\text{backpatch}(\{102\}, 104)$

$S.\text{nextlist} = \{105\}$

$\text{backpatch}(\{104\}, 105)$

Array Elements

- Array elements are numbered $0, \dots, n-1$
- Let w be the width of each array element
- Let base be the address of the storage allocated for the array
- Then the i^{th} element $A[i]$ begins in location $\text{base} + i * w$
- The element $A[i][j]$ with n elements in the 2nd dimension begins at: $\text{base} + (i * n + j) * w$

```
void foo(int[] arr)
    { arr[1] = arr[0] * 2 }
```

Array References

foo:

```
t0 = 1
t1 = 4
t2 = t1 * t0
t3 = arr + t2
t4 = *(t3)
t5 = 0
t6 = 4
t7 = t6 * t5
t8 = arr + t7
t9 = *(t8)
t10 = 2
t11 = t9 * t10
t4 = t11
```

Wrong

foo:

```
t0 = 1
t1 = 4
t2 = t1 * t0
t3 = arr + t2
t4 = 0
t5 = 4
t6 = t5 * t4
t7 = arr + t6
t8 = *(t7)
t9 = 2
t10 = t8 * t9
*(t3) = t10
```

Correct

```
int factorial(int n)
{
    if (n<=1) return 1;
    return n*factorial(n-1);
}
```

```
void main()
{
    print(factorial(6));
}
```

factorial:

t0 = 1

t1 = n lt t0

t2 = n eq t0

t3 = t1 or t2

ifFalse t3 goto end

t4 = 1

return t4

end:

t5 = 1

t6 = n - t5

t7 = call factorial (t6)

t8 = n * t7

return t8

t3 = n <= 1

Implementing IR

- Quadruples:

t1 = - c

t2 = b * t1

t3 = - c

t4 = b * t3

t5 = t2 + t4

a = t5

op	arg1	arg2	result
minus	c		t1
*	b	t1	t2
minus	c		t3
*	b	t3	t4
+	t2	t4	t5
=	t5		a

Implementing IR

- Triples

1. - c

2. b * (1)

3. - c

4. b * (3)

5. (2) + (4)

6. a = (5)

	op	arg1	arg2
(1)	minus	c	
(2)	*	b	(1)
(3)	minus	c	
(4)	*	b	(3)
(5)	+	(2)	(4)
(6)	=	a	(5)

We refer to results of an operation **x op y** by its position

Code optimizer can change the order of instructions

Implementing IR

Instruction List:

35	(1)
36	(2)
37	(3)
38	(4)
39	(5)
40	(6)

- Indirect Triples

1. - c
2. b * (1)
3. - c
4. b * (3)
5. (2) + (4)
6. a = (5)

can be re-ordered
by the code
optimizer

	op	arg1	arg2
1	minus	c	
2	*	b	(1)
3	minus	c	
4	*	b	(3)
5	+	(2)	(4)
6	=	a	(5)

Implementing IR

- Static Single Assignment (SSA): All assignments are to variables with distinct names

instead of:

$a = t1$

$b = a + t1$

$a = b + t1$

the SSA form has:

$a1 = t1$

$b1 = a1 + t1$

$a2 = b1 + t1$

a variable is never reassigned

Correctness vs. Optimizations

- When writing backend, correctness is paramount
 - Efficiency and optimizations are secondary concerns at this point
- Don't try optimizations at this stage

Summary

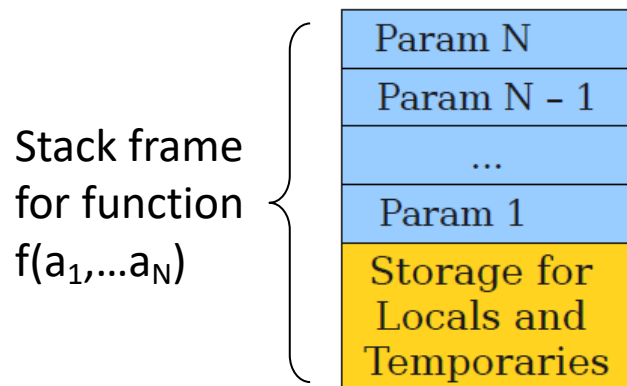
- 3-address code (TAC) is one example of an intermediate representation (IR)
- An IR should be close enough to existing machine code instructions so that subsequent translation into assembly is trivial
- In an IR we ignore some complexities and differences in computer architectures, such as limited registers, multiple instructions, branch delays, load delays, etc.

Extra Slides

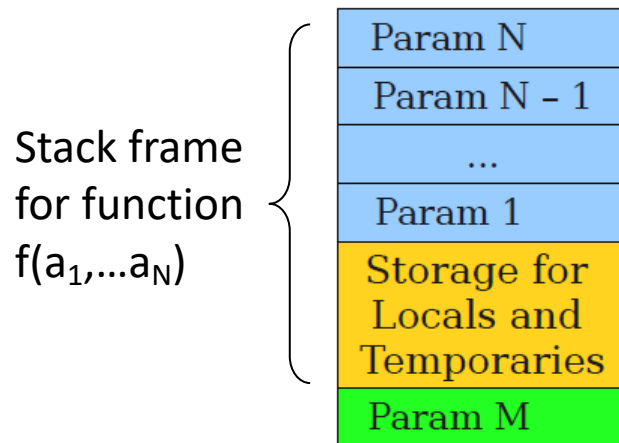
What TAC doesn't give you

- Check bounds (array indexing)
- Two or n-dimensional arrays
- Conditional branches other than **if** or **ifFalse**
- Field names in records/structures
 - Use base+offset load/store
- Object data and method access

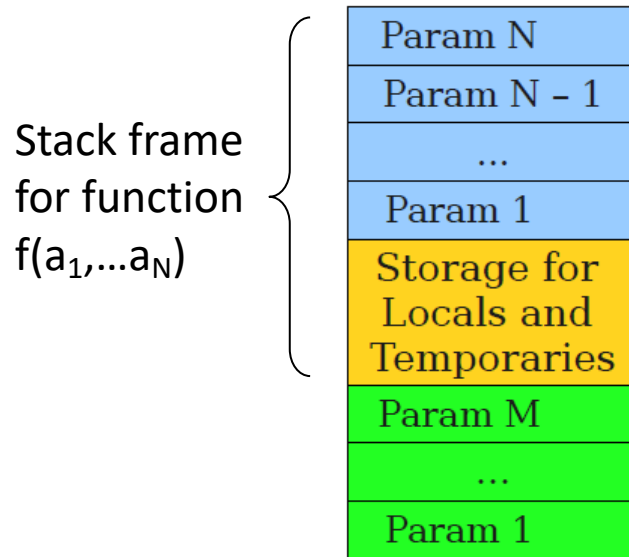
Function arguments



Function arguments



Function arguments

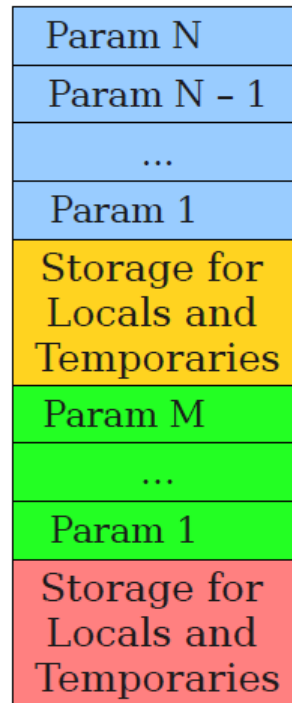


Function arguments

- Usually, stacks start at high memory addresses and grow to low memory addresses.

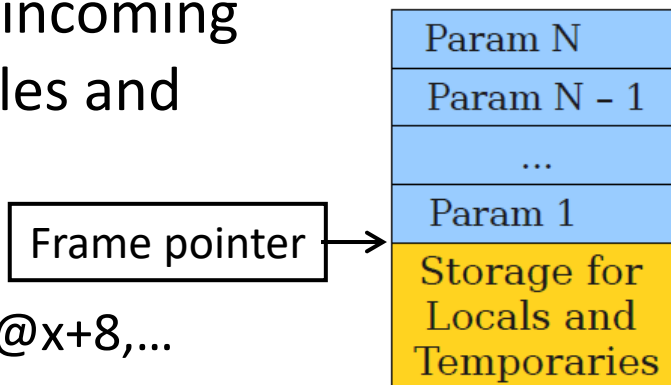
Stack frame
for function
 $f(a_1, \dots, a_N)$

Stack frame
for function
 $g(a_1, \dots, a_M)$



Function arguments

- Compute offsets for all incoming arguments, local variables and temporaries
 - Incoming arguments are at offset $@x$, $@x+4$, $@x+8, \dots$
 - Locals+Temps are at $@-y-4$, $@-y-8$, ...



Computing Location Offsets

```
class A {  
  
    void f (int a /* @x+4 */,  
            int b /* @x+8 */,  
            int c /* @x+12 */) {  
  
        int s    /* @-y-4 */  
  
        if (c > 0) {  
            int t ...    /* @-y-8 */  
  
        } else {  
            int u    /* @-y-12 */  
            int t ...    /* @-y-16 */  
  
        }  
    }  
}
```

Location offsets for
temporaries are ignored
on this slide



You could reuse **@-y-8** here,
but okay if you don't